

On Φ -Recurrent Lorentzian α -Sasakian manifold with semi symmetric Non metric connection

*Dr. Kripa Sindhu Prasad**

Abstract

The present work deals with the study of Φ -recurrent Lorentzian α -Sasakian manifold with semi-symmetric non metric connection.

Keywords : Locally Φ -symmetric manifold Φ -recurrent Lorentzian α -Sasakian manifold, η η - Einstein manifold.

Introduction

The notion of local symmetry of a Riemannian manifold has been studied by many authors in several ways to a different extent. In 1977, Taka hasi[9] introduced the notion of locally Φ -symmetric Sasakian manifold and obtained their several interesting results. Generalizing the notion of Φ -symmetry, De, U.C[4] introduced the notion of Φ -recurrent Sasakian manifold.

Fridmann and Schouten introduced the idea of semi-symmetric linear connection on a differentiable manifold. Hayden introduced the idea of metric connection with torsion on Riemannian manifold. Yano[8], Golab [5] defined and studied semi-symmetric and quarter symmetric connection with affine connection. Further many authors like De,U.C.[1], Sharfudin and Hussain[3], Rastogi, Mishra and Pandey, Bagewadi and many other studied the various properties of semi-symmetric connection.

In this paper we study Φ -recurrent Lorentzian α -Sasakian manifold with semi-symmetric non metric connection and proved that a Φ -recurrent Lorentzian α -Sasakian manifold with symmetric non metric connection is a η η - Einstein manifold. Further we show that in Φ -recurrent Lorentzian α -Sasakian manifold with semi-symmetric non metric connection, the characteristic vector ξ and vector field η associated to the 1- form A are co-directional.

Preliminaries

A differentiable manifold M of dimension n is called a Lorentzian α sasakian

**Associate professor, Department of Mathematics, Thakur Ram Multiple Campus Birgunj, Tribhuwan University, Nepal*

manifold of it admints a tensor field Φ of type (1,1), the characteristic vector ξ , a covariant vector field η and lorentzian metric g which satisfy

$$\Phi^2 \Phi^2 = 1 + \eta \otimes \xi \tag{2.1}$$

$$\eta(\xi) = -1 \tag{2.2}$$

$$g(\Phi X, \Phi Y) = g(X, Y) + \eta(X) \eta(Y) \tag{2.3}$$

$$g(X, \xi) = \eta(X) \tag{2.4}$$

$$\Phi \xi = 0, \eta(\Phi X) = 0 \tag{2.5}$$

$$(D_x D_x \Phi)Y = \alpha g(X, Y) \xi - \alpha \eta(Y)X \tag{2.6}$$

for all $X, Y \in Tm [2,3,13]$

Also a lorentzian α sasakian manifold m satisfies

$$(D_x D_x \xi)Y = \alpha \Phi X \tag{2.7}$$

$$(D_x D_x \eta)Y = -\alpha g(\Phi X, Y) \tag{2.8}$$

Where D denotes the operator of covariant differentiation with respect to lorentzian matric g .

Also on a Lorentzian α sasakian manifold , the following hold [2,3,13]

$$R(X, Y) \xi = \alpha^2 \alpha^2 (\eta(Y)X - \eta(X)Y) \tag{2.9}$$

$$R(\xi, X)Y = \alpha^2 \alpha^2 (g(X, Y) \xi - \eta(Y)X) \tag{2.10}$$

$$R(\xi, X) \xi = \alpha^2 \alpha^2 (\eta(X) \xi + X) \tag{2.11}$$

$$S(X, \xi) = (n-1) \alpha^2 \alpha^2 \eta(X) \tag{2.12}$$

$$\eta(R(X, Y)Z) = \alpha^2 \alpha^2 (g(Y, Z) \eta(X) - g(X, Z) \eta(Y)) \tag{2.13}$$

$$g(R(\xi, X)Y, \xi) = -\alpha^2 \alpha^2 [g(X, Y) + \eta(X) \eta(Y)] \tag{2.14}$$

For any vector field X, Y, Z where S is the Ricci curvature and Q is the Ricci operation given by

$$S(X, Y) = g(\Phi X, Y)$$

A lorentzian α sasakian manifold is said to be η - Einstein manifold if its Ricci tensor S takes the form

$$S(X, Y) = a g(X, Y) + b \eta(X) \eta(Y)$$

for arbitrary vector X, Y where a and b are function on M . If $b=0$ the η - Einstein manifold becomes Einstein manifold. [3,9] have proved that if Lorentzian α sasakian manifold M is η -

Einstein manifold then $a + b = -\alpha^2 - \alpha^2 (n-1)$.

Definition 2.1: A Lorentzian α sasakian manifold is said to be locally Φ - symmetric if

$$\Phi^2 \Phi^2 ((D_w D_w R) (X, Y)Z) = 0 \quad (2.15)$$

Definition : 2.2

A Lorentzian α sasakian manifold is said to be recurrent if there exists a non zero 1-form A such that

$$\Phi^2 \Phi^2 ((D_w D_w R) (X, Y)Z) = A(W)R(X, Y)Z, \quad (2.16)$$

Where A(W) is defined by $A(W) = g(W, \rho)$ and ρ is a vector field associated with 1-form.

Lorentzian α sasakian manifold with semi symmetric non metric connection:

A semi symmetric connection $\bar{D} \bar{D}$ in Lorentzian α sasakian manifold can be defined by

$$\bar{D}_x \bar{D}_x Y = \bar{D}_x \bar{D}_x Y + \eta(Y)X \quad (3.1)$$

$$\text{Also we have } (\bar{D}_x \bar{D}_x g)(Y, Z) = -\eta(Y)g(Y, Z) - \eta(Z)g(Y, X) \quad (3.2)$$

A connection given by (3.1) with (3.2) is called semi symmetric non metric connection in Lorentzian α sasakian manifold.

A relation between curvature tensor M of the manifold with semi metric connection non metric connection $\bar{D} \bar{D}$ and Levi- Civita connection D is given by

$$\bar{R} \bar{R}(X, Y)Z = R(X, Y)Z - \alpha g(\Phi X, Z)Y - \alpha g(\Phi Y, Z)X \quad (3.3)$$

Where $\bar{R} \bar{R}$ and R are the Riemannian curvature of the connections $\bar{D} \bar{D}$ and D respectively.

$$\text{From (3.3) , we have } \bar{S} \bar{S} (Y, Z) = S(Y, Z) + \alpha(n-1) g(\Phi Y, Z) \quad (3.4)$$

Where $\bar{S} \bar{S}$ and S are the Ricci tensor of the connections $\bar{D} \bar{D}$ and D respectively.

$$\text{Contracting (3.4), we get } \bar{r} \bar{r} = r \quad (3.5)$$

Where $\bar{r} \bar{r}$ and r are the scalar curvatures of the connections $\bar{D} \bar{D}$ and D respectively.

Φ - recurrent Lorentzian α sasakian manifold with semi symmetric non metric connection.

A analogous to the definition (2.2) we define a Lorentzian α sasakian manifold is said to be Φ - recurrent with respect to semi symmetric non metric connection if its curvature tensor $\bar{R}\bar{R}$ satisfies the following condition

$$\Phi^2 \Phi^2 (D_w D_w \bar{R}\bar{R})(X, Y) Z = A(W) \bar{R}A(W) \bar{R}(X,Y)Z \quad (4.1)$$

using (2.1) in (4.1), we get

$$(\bar{D}_w \bar{R}(\bar{D}_w \bar{R})(X, Y) Z + \eta((\bar{D}_w \bar{R}(\bar{D}_w \bar{R}))(\bar{D}_w \bar{R})(X,Y)Z)\xi = A(W) \bar{R}\bar{R}(X, Y)Z \quad (4.2)$$

from which it follows that

$$\begin{aligned} &g((\bar{D}_w \bar{R}(\bar{D}_w \bar{R}))(\bar{D}_w \bar{R})(X, Y)Z, U) + \eta((\bar{D}_w \bar{R}(\bar{D}_w \bar{R}))(\bar{D}_w \bar{R})(X,Y)Z)g(\xi, U) \\ &= A(W)g(\bar{R}\bar{R}(X, Y)Z, U) \end{aligned} \quad (4.3)$$

Let $\{e_i, e_1\}$, $i = 1,2,3,\dots, n$ be an orthonormal basis of the tangent space at any point of the manifold. Then putting $X = U = \{e_i, e_1\}$ in (4.3) and taking summation over i , $1 \leq i \leq n$, we get

$$((\bar{D}_w \bar{S}(\bar{D}_w \bar{S}))(Y,Z) + \eta((\bar{D}_w \bar{R}(\bar{D}_w \bar{R}))(e_1 e_1, Y)Z)\eta(e_1 e_1) = A(W) \bar{S}\bar{S}(Y, Z) \quad (4.4)$$

putting $Z = \xi$, in (4.4), the second term of (4.4) takes the form

$g((\bar{D}_w \bar{R}(\bar{D}_w \bar{R}))(e_1 e_1, Y) \xi, \xi)$ which on simplification gives

$$g((\bar{D}_w \bar{R}(\bar{D}_w \bar{R}))(e_1 e_1, Y) \xi, \xi) = 0$$

Then from (4.4) we obtain

$$(\bar{D}_w \bar{S}(\bar{D}_w \bar{S}))(Y, \xi) = A(W) \bar{S}\bar{S}(Y, \xi) \quad (4.5)$$

Now we know that

$$(\bar{D}_w \bar{S}(\bar{D}_w \bar{S}))(Y, \xi) = \bar{D}_w \bar{S} \bar{D}_w \bar{S}(Y, \xi) - \bar{S}(\bar{D}_w \bar{S}(\bar{D}_w Y, \xi) - \bar{S}\bar{S}(Y, \bar{D}_w \xi \bar{D}_w \xi)) \quad (4.6)$$

Using (2.7), (2.8), (2.12), (3.4) in (4.6), we get

$$\begin{aligned} &(\bar{D}_w \bar{S}(\bar{D}_w \bar{S}))(Y, \xi) = \alpha S(Y, \Phi W) + S(Y, W) - \alpha(\alpha + 1)(n-1)g(Y, \Phi W) - \alpha^2 \alpha^2 (n-1)g(Y, W) \\ &+ \alpha^2 \alpha^2 (n-1)g(\Phi Y, \Phi W) \end{aligned} \quad (4.7)$$

In view of (4.5) and (4.7), we get

$$\alpha S(Y, \Phi W) + S(Y, W) - \alpha(\alpha + 1)(n-1)g(Y, \Phi W) - \alpha^2 \alpha^2 (n-1)g(Y, W) + \alpha^2 \alpha^2 (n-1)g(\Phi Y, \Phi W) = \alpha^2 \alpha^2 (n-1)A(W)\eta(Y)$$

Replacing $Y = \Phi Y$ in above equation, we get

$$\alpha S(\Phi Y, \Phi W) + S(\Phi Y, W) - \alpha(\alpha + 1)(n-1)g(\Phi Y, \Phi W) - \alpha^2 \alpha^2 (n-1)g(\Phi Y, W)$$

$$+ \alpha^2 \alpha^2 (n - 1) g(Y, \Phi W) = 0 \tag{4.8}$$

Interchanging Y and W in (4.8) we get

$$\alpha S(\Phi W, \Phi Y) + S(\Phi W, Y) - \alpha(\alpha + 1)(n - 1)g(\Phi W, \Phi Y) - \alpha^2 \alpha^2 (n - 1)g(\Phi W, Y) + \alpha^2 \alpha^2 (n - 1) g(W, \Phi Y) = 0 \tag{4.9}$$

Adding (4.8) and (4.9) and simplifying we get

$$S(\Phi Y, \Phi W) = (\alpha^2 \alpha^2 + 1)(n-1)g(\Phi Y, \Phi W)$$

Using (2.3) and (2.15), we get

$$S(Y, W) = (\alpha^2 \alpha^2 + 1)(n-1)g(Y, W) + (n - 1) \eta(Y) \eta(W)$$

This leads to the following theorem .

Theorem 4.1: A Φ - recurrent Lorentzian α sasakian manifold with semi symmetric non metric connection is η - Einstein manifold.

Again from (4.2), we have

$$(\bar{D}_W \bar{R} (\bar{D}_W \bar{R}))(X, Y)Z = - \eta((\bar{D}_W \bar{R} (\bar{D}_W \bar{R}))(X, Y)Z) \xi \xi + A(W) \bar{R} \bar{R} (X, Y) \tag{4.10}$$

From (2.13), (3.3) and using Bainchi identity we get

$$A(W) \eta(\bar{R} \bar{R})(X, Y)Z + A(X) \eta(\bar{R} \bar{R})(Y, W)Z + A(Y) \eta(\bar{R} \bar{R})(W, X)Z = 0 \tag{4.11}$$

From(2.13), (3.3) in (4.11) we get

$$A(W) \alpha^2 \alpha^2 [g(Y, Z) \eta(X) - g(X, Z) \eta(Y)] + A(X) \alpha^2 \alpha^2 [g(Z, W) \eta(Y) - g(Y, Z) \eta(W)] + A(W) \alpha^2 \alpha^2 [g(X, W) \eta(Z) - g(Z, W) \eta(X)] + \alpha[g(\Phi Y, Z) \eta(X) - g(\Phi X, Z) \eta(Y) + g(\Phi W, Z) \eta(Y) - g(\Phi Y, Z) \eta(W) + g(\Phi X, Z) \eta(W) - g(\Phi W, Z) \eta(X)] = 0 \tag{4.12}$$

Putting $Y = Z = e_1 e_1$ in (4.12) and taking summation over $i, 1 \leq i \leq n$,

$$\text{we get } A(W) \eta(X) = A(X) \eta(W) \tag{4.13}$$

For all vector fields, W. Replacing X by $\xi \xi$ in (4.13), we get

$$A(W) = - \eta(\rho) \eta(W) \tag{4.14}$$

For any vector field W, where $A(\xi \xi) = g(\xi \xi, \rho \rho) = \eta(\rho)$, $\rho \rho$ being vector field associated to the

1- form A that is $g(X, \rho \rho) = A(X)$

From (4.13) and (4.14) we state that following .

Theorem 4.2: In a Φ - recurrent Lorentzian α sasakian manifold with semi symmetric non metric connection the characteristic vector ξ and vector field ρ associated to the 1- form A are codirectional and 1- form A is given by (4.14).

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